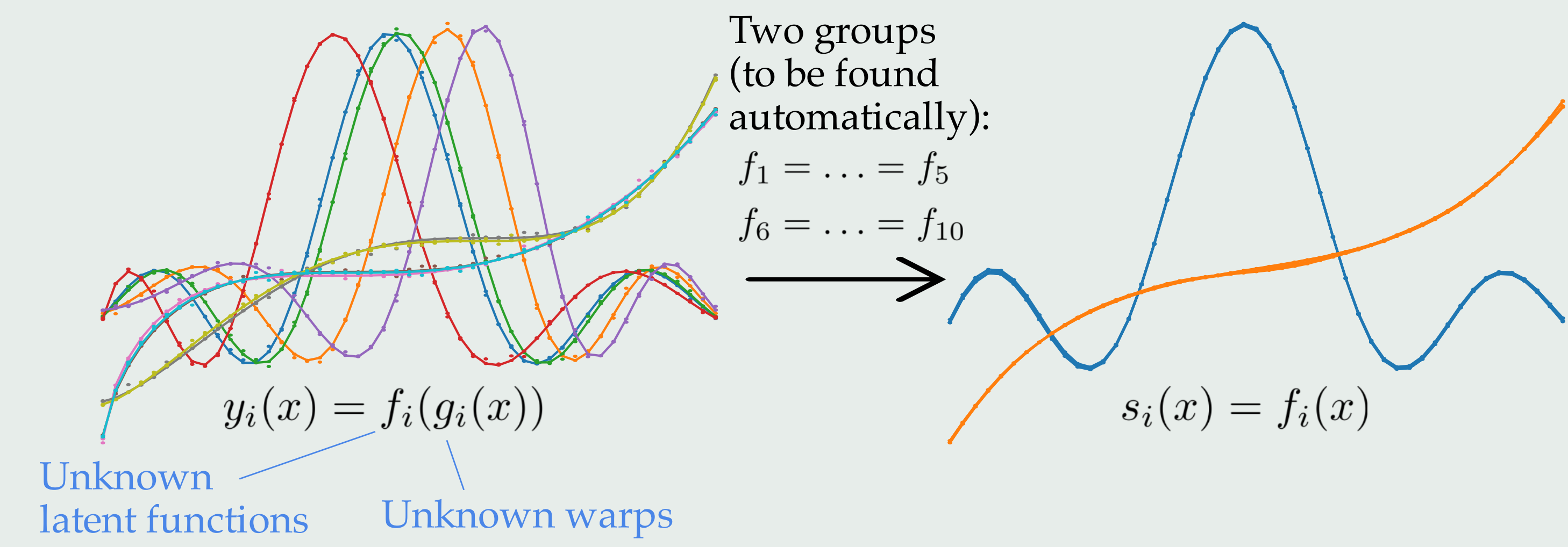


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1. INTRODUCTION

PROBLEM: aligning temporally warped noisy sequences.



CHALLENGES:

- Unknown number of distinct latent functions f_j (or equivalently, unknown number of groups of sequences).
- Weak assumptions on the warps (smoothness, monotonicity) without a parametric description.
- Sequences of different lengths.

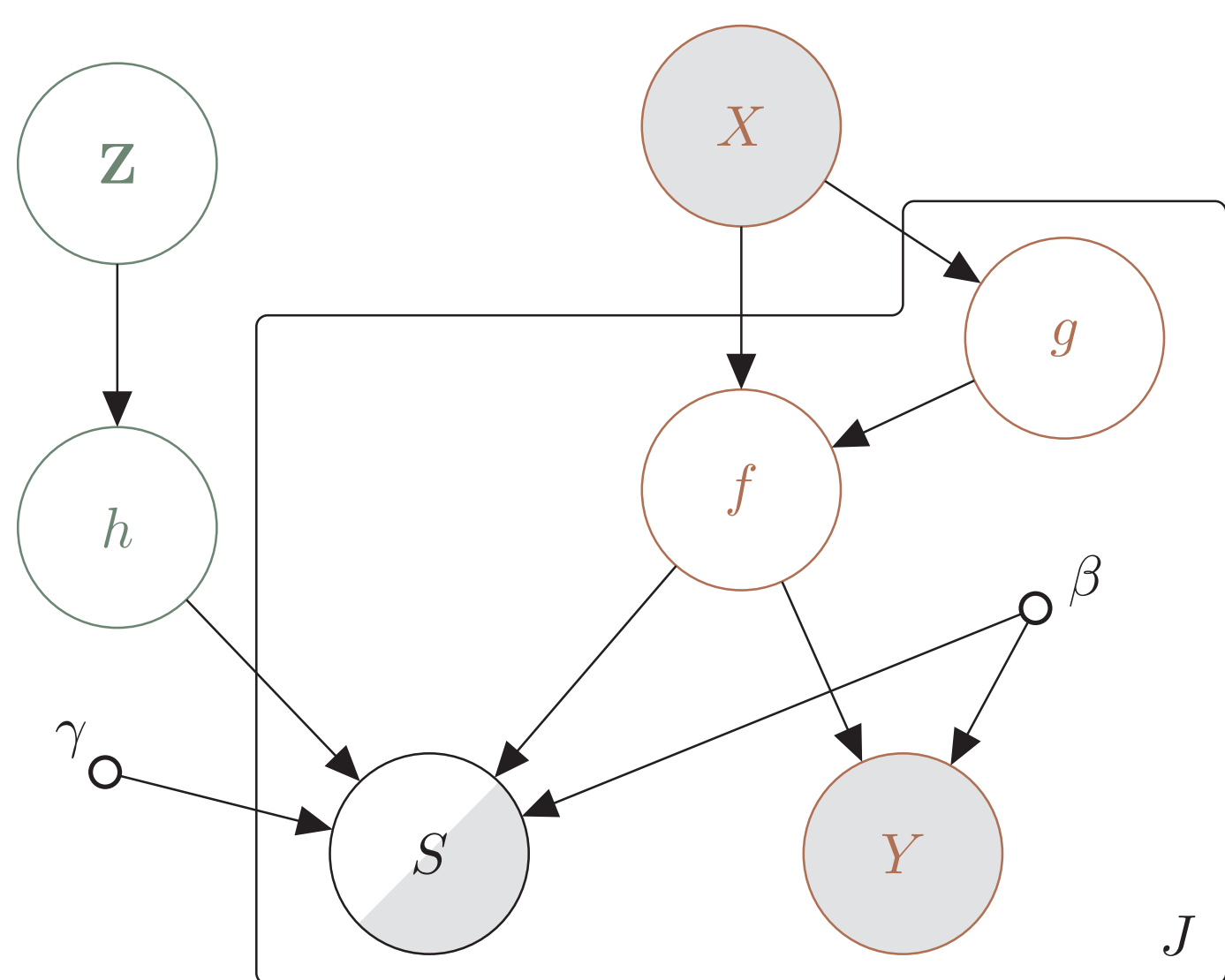
2. OVERVIEW

There are **two** parts to our model.

- We place GP priors on f_j and g_j .
 - Fit these GPs on the observed sequences y_j .
- MODEL OVER TIME

This describes each observed sequence in isolation without aligning them. Moreover, fitting both f_j and g_j to a single sequence y_j is an ill-posed problem. To address this, we:

- Evaluate estimated f_i at fixed inputs x : $S_j = f_j(x) + \epsilon_j$.
 - Impose a constraint encouraging $\{S_j\}$ to split into a small number of clusters.
 - Define this constraint using GP-LVM.
- ALIGNMENT MODEL



GOAL: find the aligned sequences $\{S_j\}$ which have high likelihood under both parts of the model.

3. MODEL

INPUTS:

$Y_j \in \mathbb{R}^N$ - observed sequences
 $X \in \mathbb{R}^N$ - observed (fixed) uniform sampling of time

WARPINGS:

The time warpings g_j need to be monotonic, which we ensure by parametrising them using auxiliary variables $U_j \in \mathbb{R}^N$ such that $[G_j]_n := 2 \sum_{k=1}^n [\text{softmax}(U_j)]_k - 1$.

MODEL OVER TIME:

Warps evaluated at fixed inputs ($g_j(X)$) Fixed inputs Kernel hyperparams

Prior over warps: $p(G_j | X, \omega) \sim \mathcal{N}(0, k_{\omega_j}(X, X))$

Prior over sequences: $p\left(\begin{bmatrix} F_j^X \\ F_j^G \end{bmatrix} | G_j, X_j, \theta_j\right) \sim \mathcal{N}\left(\mathbf{0}, \begin{bmatrix} k_{\theta_j}(X, X) & k_{\theta_j}(X, G_j) \\ k_{\theta_j}(G_j, X) & k_{\theta_j}(G_j, G_j) \end{bmatrix}\right)$

Latent function GP evaluated at fixed inputs $f_j(X)$ Latent function GP evaluated at warped inputs $f_j(G_j)$

ALIGNMENT MODEL:

We use a GP-LVM that places independent GPs over the data features.

LIKELIHOODS:

We treat S as if they are observed (see Limitations) calling them *pseudo-observations* with the likelihood defined as an equal mixture:

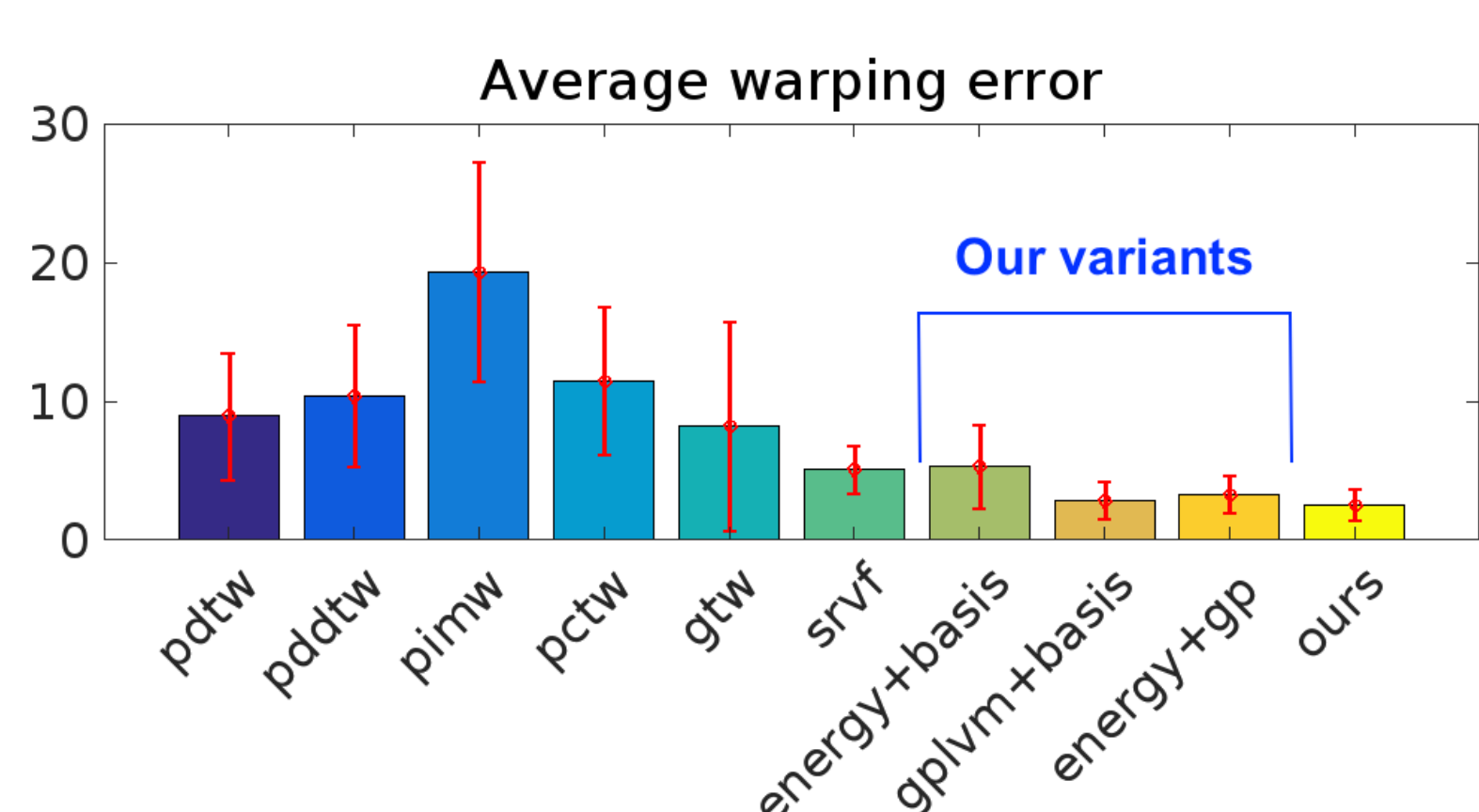
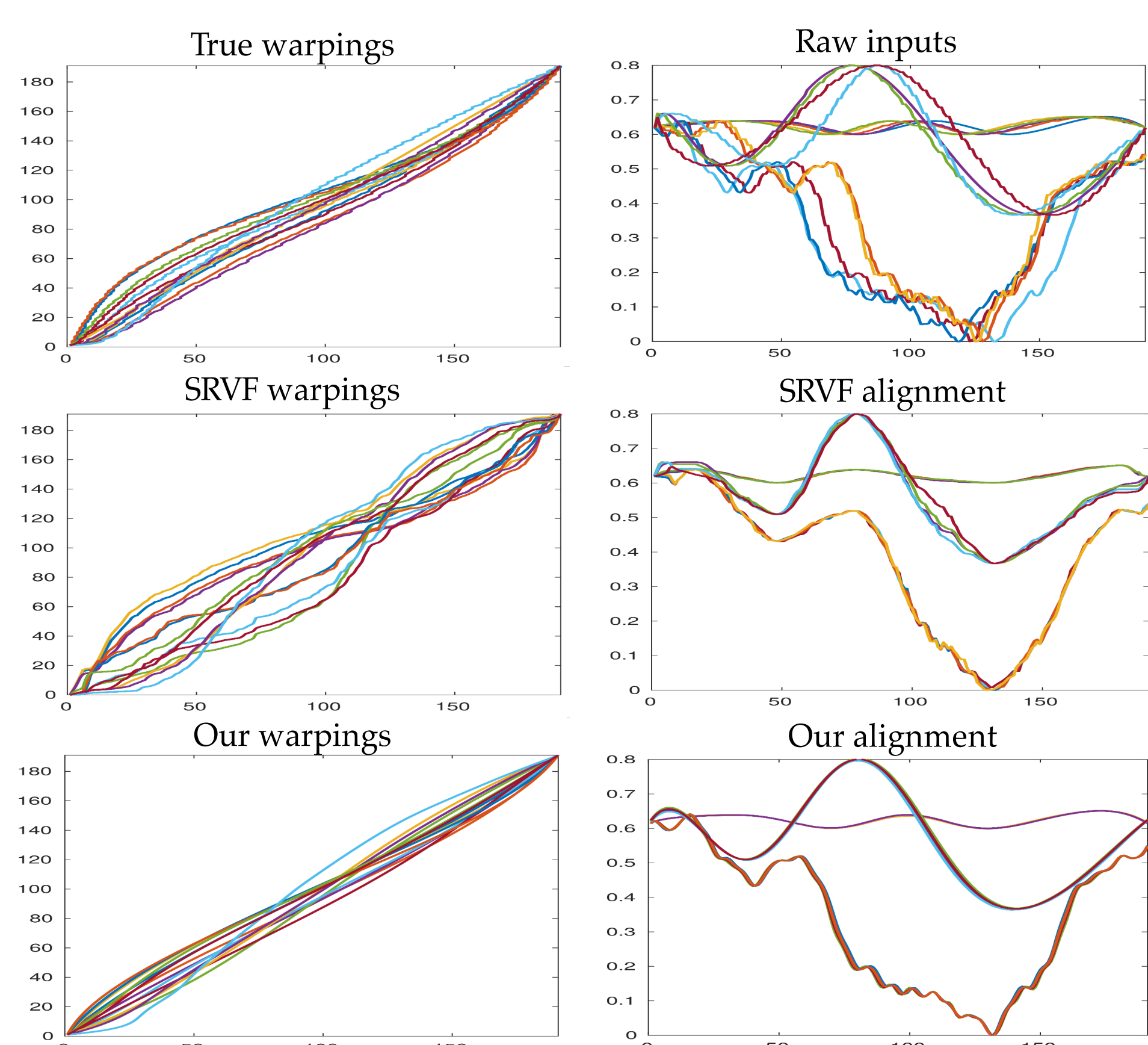
Latent functions evaluated at fixed inputs GP-LVM latent space Vector of n-th samples of aligned sequences j-th aligned sequence

Aligned sequences Noiseless GP-LVM evaluations Factorisation over columns of S Factorisation over rows of S

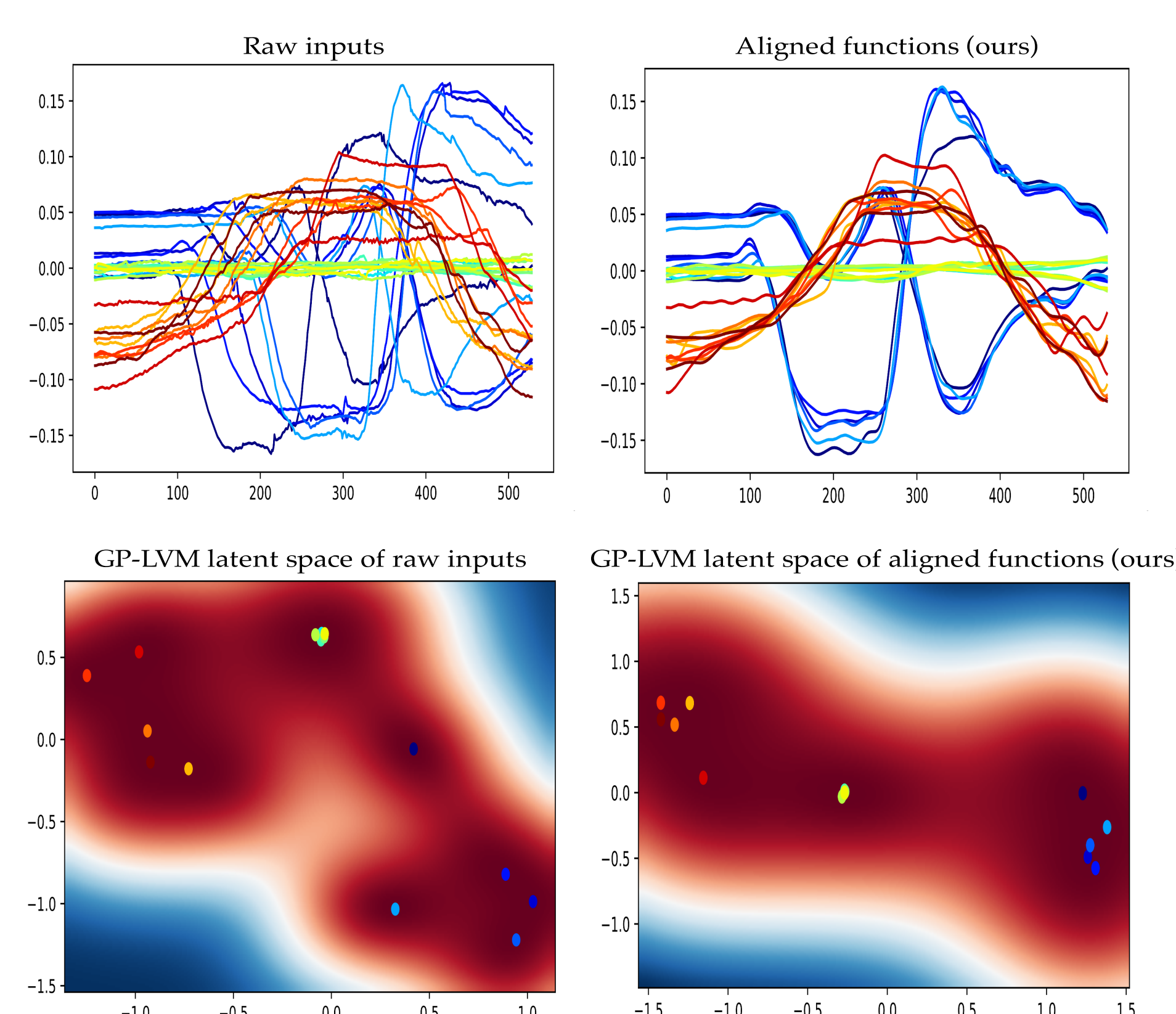
Raw inputs, Y Aligned data (pseudo-observations), S

$p(S | \mathbf{H}, \mathbf{F}^X, \mathbf{Z}) = \frac{1}{2} \left(\prod_n \mathcal{N}(S_{:,n} | \mathbf{H}_n, \gamma^{-1} I_J) + \prod_j \mathcal{N}(S_{j,:} | \mathbf{F}_j^X, \beta_j^{-1} I_N) \right)$

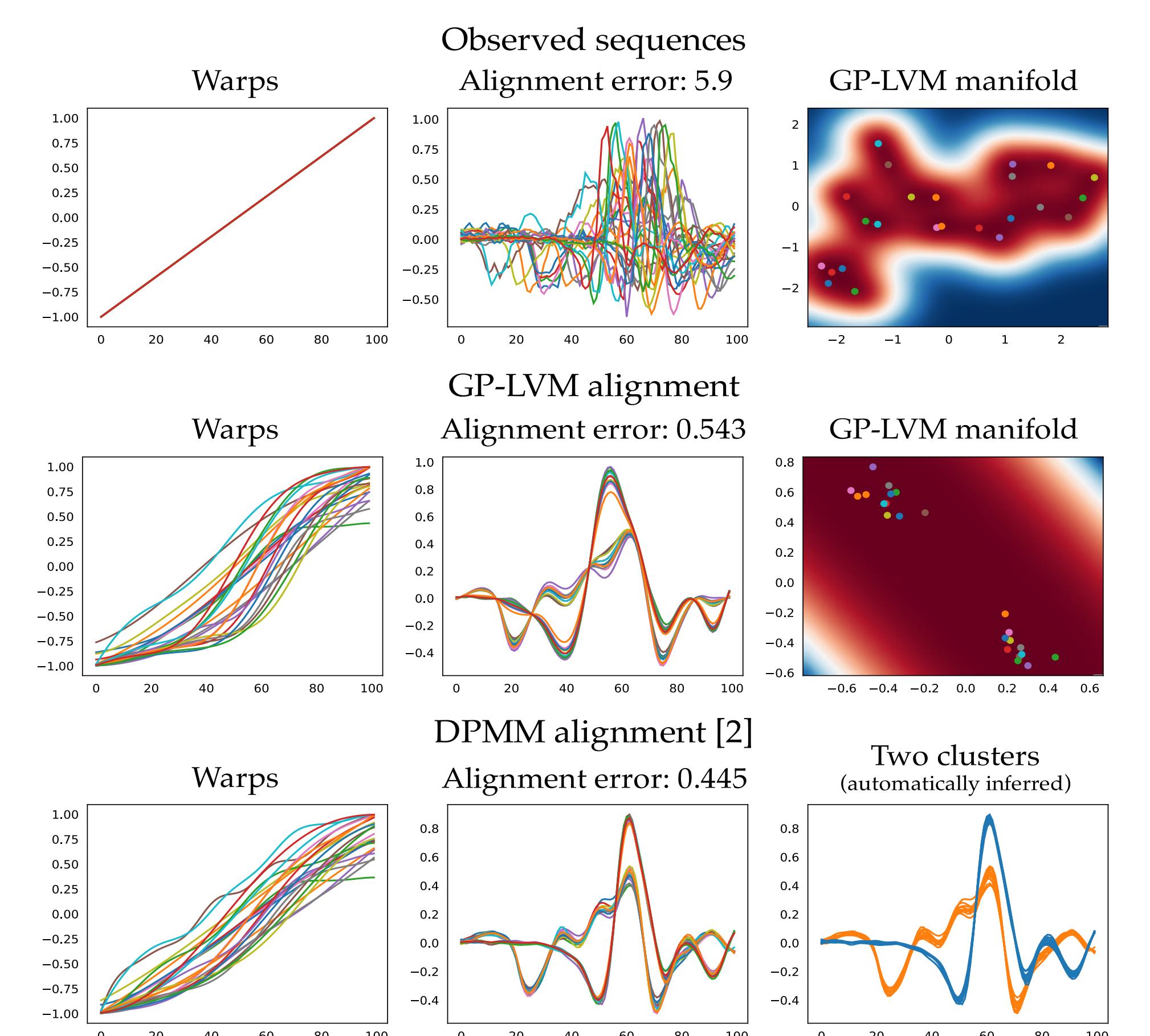
5. COMPARISONS [3, 4]



6. CMU MOTION CAPTURE DATA



7. HEARTBEATS DATA [1]



8. LIMITATIONS

- S needs to be observed for the two parts of the model to be conditionally dependent, thus, we directly optimise S obtaining a point estimate of the aligned sequences. How to make the model fully generative?
- Scalability (beyond sparse GPs)

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- [3] S. Kurtk, A. Srivastava, E. Klassen, Z. Ding. Statistical Modeling of Curves using Shapes and Related Features. Journal of the American Statistical Association, 2012.
- [4] F. Zhou, F. de al Torre. Generalized Canonical Time Warping. IEEE Transactions on Pattern Analysis and Machine Intelligence (PAMI), 2016.